Integration by Parts

$$\int u dv = uv - \int v du$$

∡ Integral of Log

$$\int \ln x dx = x \ln x - x + C.$$

Taylor Series

If the function f is "smooth" at x = a, then it can be approximated by the n^{th} degree polynomial

$$f(x) \approx f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \cdots + \frac{f^{(n)}(a)}{n!}(x - a)^n.$$

Maclaurin Series

A Taylor Series about x = 0 is called Maclaurin.

$$e^{x} = 1 + x + \frac{x^{2}}{2} + \frac{x^{3}}{3!} + \cdots$$

$$\cos(x) = 1 - \frac{x^{2}}{2} + \frac{x^{4}}{4!} - \cdots$$

$$\sin(x) = x - \frac{x^{3}}{3!} + \frac{x^{5}}{5!} - \cdots$$

$$\frac{1}{1 - x} = 1 + x + x^{2} + x^{3} + \cdots$$

$$\ln(x + 1) = x - \frac{x^{2}}{2} + \frac{x^{3}}{3} - \frac{x^{4}}{4} + \cdots$$

Trig Identities

Double-Argument $\sin 2x = 2 \sin x \cos x$ $\cos 2x = \cos^2 x - \sin^2 x = 1 - 2 \sin^2 x$ Pythagorean $\sin^2 x + \cos^2 x = 1$ (others are easily derivable by

dividing by $\sin^2 x$ or $\cos^2 x$)

* Lagrange Error Bound

If $P_n(x)$ is the n_{th} degree Taylor polynomial of f(x) about c and $\left|f^{(n+1)}(t)\right| \leq M$ for all t between x and c, then

$$|f(x) - P_n(x)| \le \frac{M}{(n+1)!} |x - c|^{n+1}$$

Alternating Series Error Bound

If $S_N = \sum_{k=1}^N (-1)^n a_n$ is the Nth partial sum of a convergent alternating series, then

$$|S_{\infty}-S_N|\leq |a_{N+1}|$$

Euler's Method

If given that $\frac{dy}{dx} = f(x, y)$ and that the solution passes through (x_0, y_0) , $y(x_0) = y_0$

:

$$y(x_n) = y(x_{n-1}) + f(x_{n-1}, y_{n-1}) \cdot \Delta x$$

In other words:

$$x_{\text{new}} = x_{\text{old}} + \Delta x$$

$$y_{\text{new}} = y_{\text{old}} + \frac{dy}{dx}\Big|_{(x_{\text{old}}, y_{\text{old}})} \cdot \Delta x$$

Ratio Test

The series $\sum_{k=0}^{\infty} a_k$ converges if

$$\lim_{k \to \infty} \left| \frac{a_{k+1}}{a_k} \right| < 1.$$

If limit equals 1, you know nothing.

Polar Curves

For a polar curve $r(\theta)$, the **Area** inside a "leaf" is

$$\int_{\theta_1}^{\theta_2} \frac{1}{2} [r(\theta)]^2 d\theta,$$

where $\theta 1$ and $\theta 2$ are the "first" two times that r=0.

The **slope** of $r(\theta)$ at a given θ is

$$\begin{aligned} \frac{dy}{dx} &= \frac{dy/d\theta}{dx/d\theta} \\ &= \frac{\frac{d}{d\theta}[r(\theta)\sin\theta]}{\frac{d}{d\theta}[r(\theta)\cos\theta]} \end{aligned}$$

l'Hopital's Rule

If
$$\frac{f(a)}{g(a)} = \frac{0}{0}$$
 or $= \frac{\infty}{\infty}$,
then $\lim_{x \to a} \frac{f(x)}{g(x)} = \lim_{x \to a} \frac{f'(x)}{g'(x)}$.

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES

θ	sin θ	cos θ	tan 0
0°	0	1	0
π/6,30°	1/2	√ 3/2	√ 3/3
37°	3/5	4/5	3/4
π/4,45°	√ 2/2	√ 2/2	1
53°	4/5	3/5	4/3
π/3,60°	√ 3/2	1/2	√ 3
π/2,90°	1	0	"∞"

^{*} means this is primarily for the BC exam

Curve sketching and analysis

y = f(x) must be continuous at each: critical point: $\frac{dy}{dx} = 0$ or <u>undefined</u>. local minimum: or <u>endpoints</u> $\frac{dy}{dx}$ goes (-,0,+) or (-,und,+) or $\frac{d^2y}{dx^2} > 0$. local maximum: $\frac{dy}{dx} \text{ goes } (+,0,-) \text{ or } (+,\text{und},-)$ or $\frac{d^2y}{dx^2} < 0.$ pt of inflection : concavity changes. $\frac{d^2y}{dx^2}$ goes (+,0,-),(-,0,+),(+,und,-), or (-,und,+)

Basic Derivatives

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\frac{d}{dx}(\tan x) = \sec^2 x$$

$$\frac{d}{dx}(\cot x) = -\csc^2 x$$

$$\frac{d}{dx}(\sec x) = \sec x \tan x$$

$$\frac{d}{dx}(\csc x) = -\csc x \cot x$$

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

$$\frac{d}{dx}(e^x) = e^x$$

More Derivatives

$$\frac{d}{dx} \left(\sin^{-1} x \right) = \frac{1}{\sqrt{1 - x^2}}$$

$$\frac{d}{dx} \left(\cos^{-1} x \right) = \frac{-1}{\sqrt{1 - x^2}}$$

$$\frac{d}{dx} \left(\tan^{-1} x \right) = \frac{1}{1 + x^2}$$

$$\frac{d}{dx} \left(\cot^{-1} x \right) = \frac{-1}{1 + x^2}$$

$$\frac{d}{dx} \left(\sec^{-1} x \right) = \frac{1}{|x|\sqrt{x^2 - 1}}$$

$$\frac{d}{dx} \left(\csc^{-1} x \right) = \frac{-1}{|x|\sqrt{x^2 - 1}}$$

$$\frac{d}{dx} \left(a^x \right) = a^x \ln a$$

$$\frac{d}{dx} \left(\log_a x \right) = \frac{1}{x \ln a}$$

Differentiation Rules

 $\begin{array}{l} \text{Chain Rule} \\ \frac{d}{dx} \left[f(u) \right] = f'(u) \frac{du}{dx} \\ \frac{dy}{dx} = \frac{dy}{du} \frac{du}{dx} \end{array}$

Product Rule $\frac{d}{dx}(uv) = u\frac{dv}{dx} + \frac{du}{dx}v$

Quotient Rule $\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{\frac{du}{dx}v - u\frac{dv}{dx}}{\sqrt{2}}$

"PLUS A CONSTANT"

The Fundamental Theorem of Calculus

$$\int_{a}^{b} f(x)dx = F(b) - F(a)$$
where $F'(x) = f(x)$.

Corollary to FTC

$$\begin{split} \frac{d}{dx} \int_{a(x)}^{b(x)} f(t) dt &= \\ f\left(b(x)\right) b'(x) - f\left(a(x)\right) a'(x) \end{split}$$

Intermediate Value Theorem

If the function f(x) is continuous on [a,b], then for any number c between f(a) and f(b), there exists a number d in the open interval (a, b) such that f(d) = c.

Rolle's Theorem

If the function f(x) is continuous on [a,b], the first derivative exist on the interval (a, b), and f(a) = f(b); then there exists a number x = c on (a, b)such that

$$f'(c) = 0.$$

Mean Value Theorem

If the function f(x) is continuous on [a,b], and the first derivative exists on the interval (a, b), then there exists a number x = c on (a, b) such that

$$f'(c) = \frac{f(b) - f(a)}{b - a}.$$

Theorem of the Mean Value i.e. Average Value If the function f(x) is continuous on

[a,b] and the first derivative exist on the interval (a,b), then there exists a number x = c on (a, b) such that

$$f(c) = \frac{\int_a^b f(x)dx}{(b-a)}.$$

This value f(c) is the "average value" of the function on the interval [a, b].

Trapezoidal Rule

$$\int_{a}^{b} f(x)dx = \frac{b-a}{2n} [f(x_0) + 2f(x_1) + \cdots + 2f(x_{n-1}) + f(x_n)]$$

Solids of Revolution and friends

Disk Method

$$\frac{\overline{SCHOS}}{V} = \pi \int_{a}^{b} \left[R(x) \right]^{2} dx$$

Washer Method

$$V = \pi \int_{a}^{b} \left([R(x)]^{2} - [r(x)]^{2} \right) dx$$

Shell Method(no longer on AP)

$$V = 2\pi \int_{a}^{b} r(x)h(x)dx$$

$$L = \int_a^b \sqrt{1 + \left[f'(x)\right]^2} dx$$

Surface of revolution (No longer on AP)

$$S = 2\pi \int_{a}^{b} r(x) \sqrt{1 + [f'(x)]^{2}} dx$$

Distance, velocity and acceleration

velocity = $\frac{d}{dt}$ (position). acceleration = $\frac{d}{dt}$ (velocity).

velocity vector =
$$\left\langle \frac{dx}{dt}, \frac{dy}{dt} \right\rangle$$
.
speed = $|v| = \sqrt{(x')^2 + (y')^2}$.

speed =
$$|v| = \sqrt{(x')^2 + (y')^2}$$
.

Distance =
$$\int_{\text{initial time}}^{\text{final time}} |v| dt$$
$$= \int_{t_0}^{t_f} \sqrt{(x')^2 + (y')^2} dt$$

average velocity = final position — initial position total time